

27 May 2019



- N.B.:** (1) Questions No.1 is compulsory.
 (2) Attempt any three questions out of remaining five questions.
 (3) Assume suitable data if required.
 (4) Figures to the right indicate full marks.

- Q 1. Solve any four 20
- Compare Impulse invariant method and BLT method.
 - If $x[n]=\{1,2,1,2\}$, determine $X[K]$ using DIF FFT.
 - State and prove frequency shifting property of DFT.
 - Write a short note on replication.
 - State advantages of digital filters.
- Q 2 a) Develop composite radix DITFFT flow graph for $N=6=2*3$. 10
 b) Design a digital Butterworth filter that satisfies following constraints using bilinear transformation method. Assume $T_s=0.1s$. 10
- $$0.8 \leq |H(e^{j\omega})| \leq 1 \quad 0 \leq \omega \leq 0.2\pi$$
- $$|H(e^{j\omega})| \leq 0.2 \quad 0.6\pi \leq \omega \leq \pi$$
- Q 3 a) Explain Dual Tone Multifrequency Detection using Goertzel's algorithm. 10
 b) Design a linear phase FIR low Pass filter of length 7 and cut off frequency 1 rad/sec using Hamming window. 10
- Q 4 a) Compute DFT of $x[n]=\{1,2,3,4,5,6,7,8\}$ using DITFFT algorithm. 10
 b) Explain Finite word length effects in digital filters. 10
- Q.5 a) Explain Architecture of TMS320C67XX DSP processor with the help of neat block Diagram 10
 b) Find DFT of $x(n)=\{1,2,3,4\}$. Using these results and not otherwise find DFT 10
- $x_1(n)=\{4,1,2,3\}$
 - $x_2(n)=\{2,3,4,1\}$
 - $x_3(n)=\{6,4,6,4\}$
- Q 6. Solve following 08
- Obtain digital filter transfer function by applying impulse invariance transfer function. 06

$$H(s) = \frac{s}{(s+5)(s+2)} \quad \text{if } T_s=0.1s.$$
 - Explain application of DSP processor to radar signal processing. 06
 - Write short note on limit cycle oscillations 06
